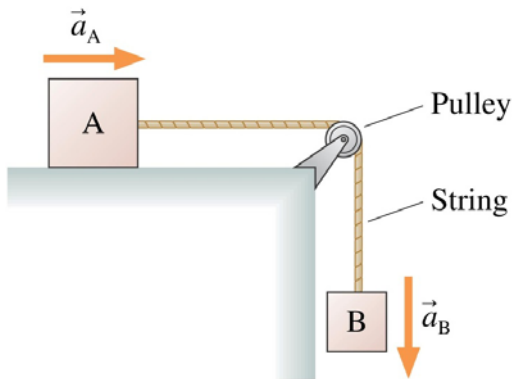


**Physics 2211K**  
**Practice for Test 2**

1. In the system sketched below, block A slides on a *frictionless surface* and the string connecting the two blocks is *massless*.

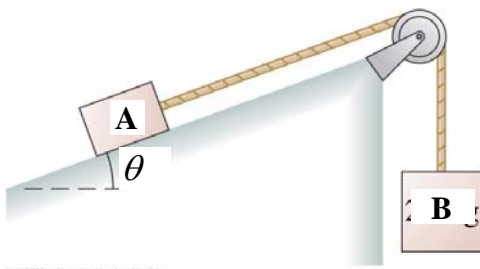


- Sketch the *free-body diagrams for masses A and B* showing all the forces acting on them.
- Write the  $F=ma$  relations for masses A and B based on the free-body diagrams of part a.
- If  $M_B = 2 \text{ kg}$  and the tension in the string  $T = 12 \text{ N}$ , calculate the acceleration of the objects.  $\boxed{4 \text{ m/s}^2}$
- If  $M_B = 2 \text{ kg}$  and the tension in the string  $T = 12 \text{ N}$ , calculate  $M_A$ .  $\boxed{3 \text{ kg}}$

2. For the system sketched above,  $M_B = 4 \text{ kg}$ ,  $M_A = 8 \text{ kg}$ ,  $\mu_s = 0.4$ , and  $\mu_k = 0.2$ . ( $g = 10 \text{ m/s}^2$ )

- Sketch the *free-body diagrams for masses A and B* showing all the forces acting on them.
- Write the  $F=ma$  relations for masses A and B based on the free-body diagrams of part a.
- Calculate the tension in the string and the acceleration of the objects if they begin from rest.  $\boxed{a = 2 \text{ m/s}^2; T = 16 \text{ N}}$
- How would part c. be different if  $\mu_s = 0.6$ , and  $\mu_k = 0.4$ ?  $\boxed{a = 0 \text{ m/s}^2; T = 40 \text{ N}}$
- Calculate how far  $M_B$  travels in  $4 \text{ s}$  if it begins from rest in part c.  $\boxed{d = 16 \text{ m}}$

3. On the sketch below, the sloping surface is frictionless.

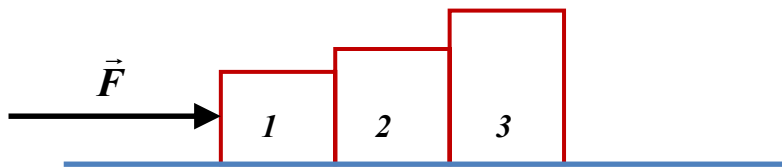


- Draw free-body diagrams for *masses A and B* showing *all the forces* acting on each.
- Use the free body diagram to write the  $F=ma$  relations for both A and B.
- If  $M_A = 2M_B$ , calculate the *angle theta* at which the *acceleration is zero*.  $\boxed{\theta = 30^\circ}$

4. Re. the set of objects sketched below:

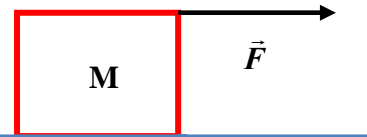
- Draw free-body diagrams for each of the masses shown (concentrate only on the horizontal forces);
- Use the free-body diagrams to write the  $F=ma$  relations for each mass;
- From the  $F=ma$  relations and Newton's 3<sup>rd</sup> law, develop expressions for the accelerations of each object;
- Develop an expression for the forces of contact with which each object acts on the one adjacent to it.
- Test your expressions for the case  $F = 70 \text{ N}$ ,  $M_1 = 2 \text{ kg}$ ,  $M_2 = 4 \text{ kg}$ , and  $M_3 = 8 \text{ kg}$  by calculating the acceleration and the forces of contact.

$$a = 5 \text{ m/s}^2; F_{2,3} = 40 \text{ N}; F_{1,2} = 60 \text{ N}$$



5. Re. the object sketched below:

- Calculate the object's acceleration from rest if the surface is frictionless,  $M = 12 \text{ kg}$ , and  $F = 50 \text{ N}$ .  $a = 4.16 \text{ m/s}^2$
- Repeat a.) for the case  $\mu_s = 0.5$  and  $\mu_k = 0.2$ .  $a = 0 \text{ m/s}^2$
- Repeat a.) for the case  $\mu_s = 0.35$  and  $\mu_k = 0.1$ .  $a = 3.17 \text{ m/s}^2$



6. Re. the object sketched below:

- Calculate the object's acceleration from rest if the surface is frictionless,  $M = 12 \text{ kg}$ , and  $F = 50 \text{ N}$ .  $a = 4.16 \text{ m/s}^2$
- Repeat a.) for the case  $\mu_s = 0.5$  and  $\mu_k = 0.2$ .  $a = 0 \text{ m/s}^2$
- Repeat a.) for the case  $\mu_s = 0.35$  and  $\mu_k = 0.1$ .  $a = 3.17 \text{ m/s}^2$



7. Re. the object sketched below:

a. Sketch the free-body diagram for the object shown showing all forces including friction;

b. Use the free-body diagram to write the  $F = ma$  relations (for horizontal & vertical directions);

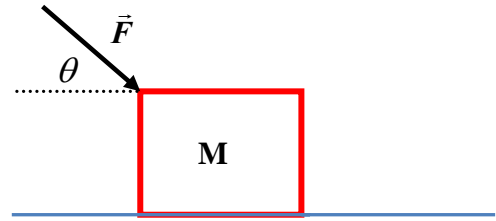
c. Use the  $F=ma$  relations to calculate the object's acceleration from rest if the surface is frictionless,  $\theta = 30^\circ$ ,  $M = 4 \text{ kg}$ , and  $F = 50 \text{ N}$ .  $a = 10.8 \text{ m/s}^2$

d. Repeat c.) for the case  $\mu_s = 0.5$  and  $\mu_k = 0.2$ .  $a = 7.6 \text{ m/s}^2$

e. Repeat c.) for the case  $\mu_s = 0.35$  and  $\mu_k = 0.1$ .  $a = 9.33 \text{ m/s}^2$

f. Repeat d.) for the case  $M = 8 \text{ kg}$ .  $a = 0 \text{ m/s}^2$

d. Challenge question: for given values of  $\theta$ ,  $M$ , and  $F$ , find an expression for the largest value  $\mu_s$  can have if there will be any acceleration at all.



8. Re. the object sketched below:

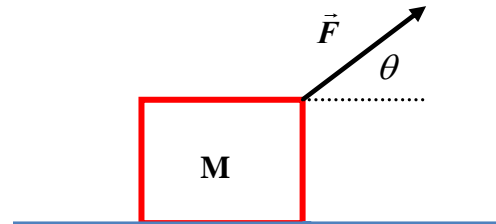
a. Sketch the free-body diagram for the object shown showing all forces including friction;

b. Use the free-body diagram to write the  $F = ma$  relations (for horizontal & vertical directions);

c. Use the  $F=ma$  relations to calculate the object's acceleration from rest if the surface is frictionless,  $\theta = 30^\circ$ ,  $M = 4 \text{ kg}$ , and  $F = 50 \text{ N}$ .  $a = 10.8 \text{ m/s}^2$

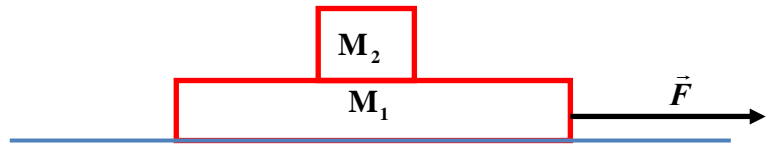
d. Repeat c.) for the case  $\mu_s = 0.5$  and  $\mu_k = 0.2$ .  $a = 10.1 \text{ m/s}^2$

e. Repeat c.) for the case  $\mu_s = 0.35$  and  $\mu_k = 0.1$ .  $a = 10.5 \text{ m/s}^2$



9. Re. the object sketched below:

- a. Sketch the free-body diagram for the object shown showing all forces including friction;  
 b. Use the free-body diagram to write the  $F = ma$  relations for  $M_1$  and  $M_2$  (for horizontal & vertical directions);



- c. For the case  $M_1 = 12 \text{ kg}$ ,  $M_2 = 4 \text{ kg}$ , and  $F = 50 \text{ N}$  calculate the acceleration of each object from rest if there is no friction either between  $M_1$  and the horizontal surface or  $M_1$  and  $M_2$ .

$$a_1 = 4.2 \text{ m/s}^2; a_2 = 0 \text{ m/s}^2$$

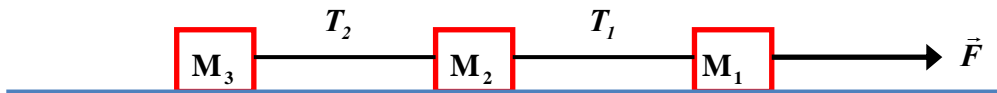
- d. Repeat part c.) for the case of friction between  $M_1$  and the horizontal surface ( $\mu_s = 0.25$  and  $\mu_k = 0.1$ ) and between  $M_1$  and  $M_2$  ( $\mu_s = 0.5$  and  $\mu_k = 0.2$ ).

$$a_1 = a_2 = 2.13 \text{ m/s}^2$$

- e. Repeat part d.) for the case  $F = 200 \text{ N}$ .

$$a_1 = 8 \text{ m/s}^2; a_2 = 2 \text{ m/s}^2$$

10. Re. the object sketched below:



- a. Sketch the free-body diagram for each mass showing all forces including friction;  
 b. Use the free-body diagrams to write the  $F = ma$  relations for each mass (for horizontal & vertical directions);  
 c. For the case of *no friction*,  $F = 500 \text{ N}$ ,  $M_1 = 12 \text{ kg}$ ,  $M_2 = 8 \text{ kg}$ , and  $M_3 = 10 \text{ kg}$ , calculate the acceleration and the tension in each string ( $T_1$  and  $T_2$ );

$$a = 16.7 \text{ m/s}^2; T_1 = 300 \text{ N}; T_2 = 166.7 \text{ N}$$

- d. Repeat c.) for the case of friction for all objects characterized by  $\mu_s = 0.5$  and  $\mu_k = 0.2$ ;

$$a = 14.7 \text{ m/s}^2; T_1 = 300 \text{ N}; T_2 = 166.7 \text{ N}$$

- e. Repeat c.) for the case of friction for each object characterized by ( $\mu_s = 0.5$  and  $\mu_k = 0.2$ ) for  $M_1$ , ( $\mu_s = 0.6$  and  $\mu_k = 0.1$ ) for  $M_2$ , and ( $\mu_s = 0.35$  and  $\mu_k = 0.1$ ) for  $M_3$ .

$$a = 15.3 \text{ m/s}^2; T_1 = 292.8 \text{ N}; T_2 = 162.7 \text{ N}$$

11. An object with *mass* = 4 kg is whirled in a vertical circular path using a string 1.2 m long.
- Sketch free-body diagrams for the object at the bottom of its path and at the top of the path;
  - Write the  $F=ma$  relations for the object at the top and the bottom of its path;
  - Use the  $F=ma$  relations to calculate the tension in the string when the object travels at  $v_t = 5 \text{ m/s}$  at the top and bottom of its path.  $T_{top} = 43.2 \text{ N}; T_{bottom} = 123.2 \text{ N}$
  - Use the  $F=ma$  relations to find the minimum speed the object can have at the top of its path for it to remain circular.  $v_{min,top} = 3.46 \text{ m/s}$
12. Mass  $M_1 = 4 \text{ kg}$  travels at  $v_1 = 20 \text{ m/s}$  in the  $+x$  direction and collides with  $M_2 = 2\text{kg}$  at rest. After the collision, they stick together. *Calculate the velocity of the combined masses after the collision.*  $v_f = 13.3 \text{ m/s, } +x \text{ direction}$
13. Mass  $M_1 = 4 \text{ kg}$  travels at  $v_1 = 20 \text{ m/s}$  in the  $+x$  direction and collides with  $M_2 = 2\text{kg}$  traveling at  $v_2 = 30 \text{ m/s}$  in the  $+y$  direction. After the collision, they stick together. *Calculate the velocity of the combined masses after the collision.*  $\vec{v}_f = (13.3 \hat{i} + 10 \hat{j}) \text{ m/s}$
14. Mass  $M_1 = 4 \text{ kg}$  travels at  $v_1 = 20 \text{ m/s}$  in the  $+x$  direction and collides with  $M_2 = 2\text{kg}$  traveling at  $v_2 = 15 \text{ m/s}$  in the  $-x$  direction. After the collision,  $M_1$  has velocity components  $v_{1fx} = +15 \text{ m/s}$  and  $v_{1fy} = -5 \text{ m/s}$ . *Calculate the velocity of  $M_2$  after the collision.*  $\vec{v}_{2f} = (20 \hat{i} + 25 \hat{j}) \text{ m/s}$