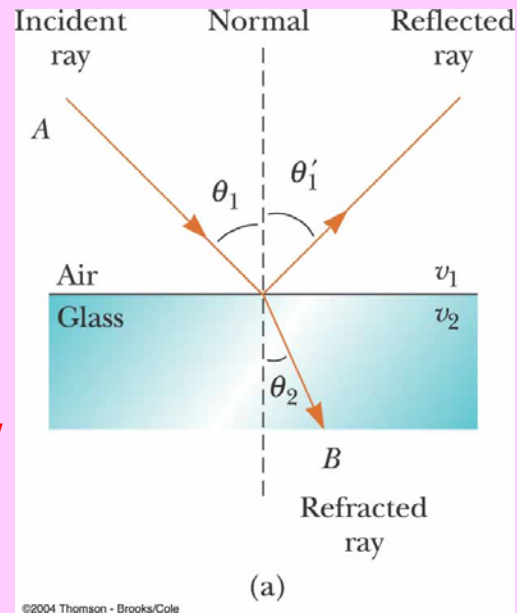


The law of reflection:

$$\theta_1 = \theta_1'$$

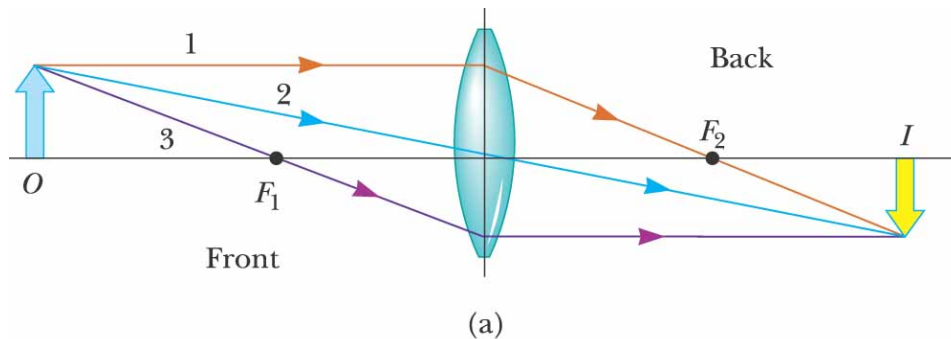
The law of refraction:

$$n_2 \sin \theta_2 = n_1 \sin \theta_1 \quad \text{Snell's Law}$$

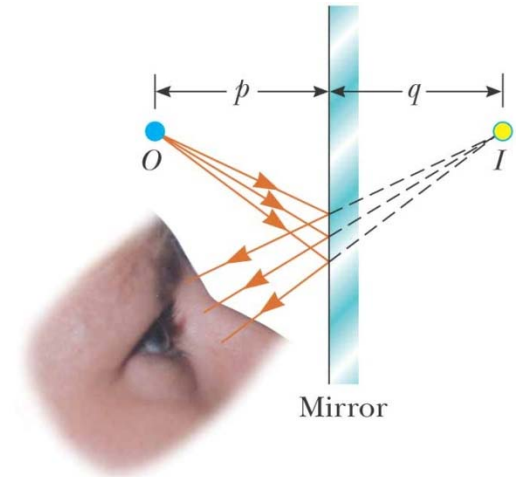


©2004 Thomson - Brooks/Cole

Image formation



©2004 Thomson - Brooks/Cole

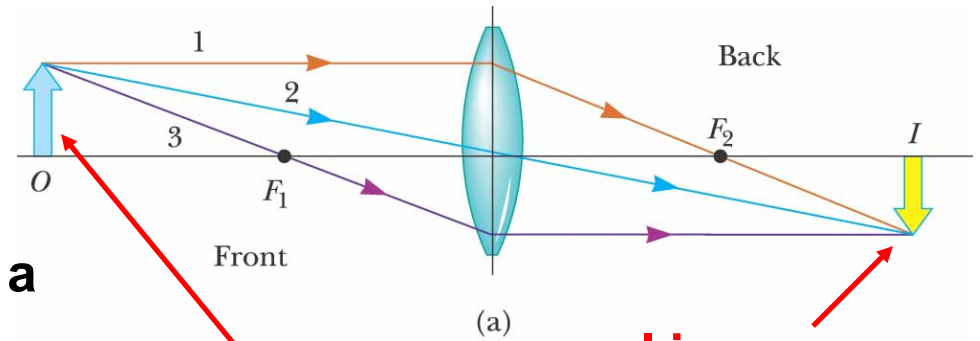


©2004 Thomson - Brooks/Cole

Chapter 23

Ray Optics - Applications: Image Formation

- Images are always located by extending diverging rays back to a point at which they intersect



©2004 Thomson - Brooks/Cole

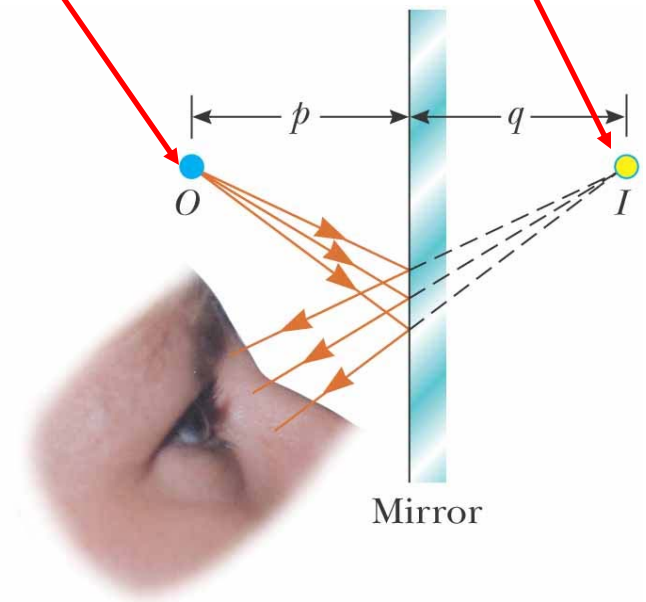
real image

- Images are located either at a point from which the rays of light **actually** diverge or at a point from which they **appear** to diverge

object

virtual image

- **To find the image it is usually enough to find intersection of just two rays!**



©2004 Thomson - Brooks/Cole

- **Magnification = $\frac{\text{image height}}{\text{object height}}$**

Flat Refracting Surface

$$n_2 \sin \theta_2 = n_1 \sin \theta_1$$

Snell's Law

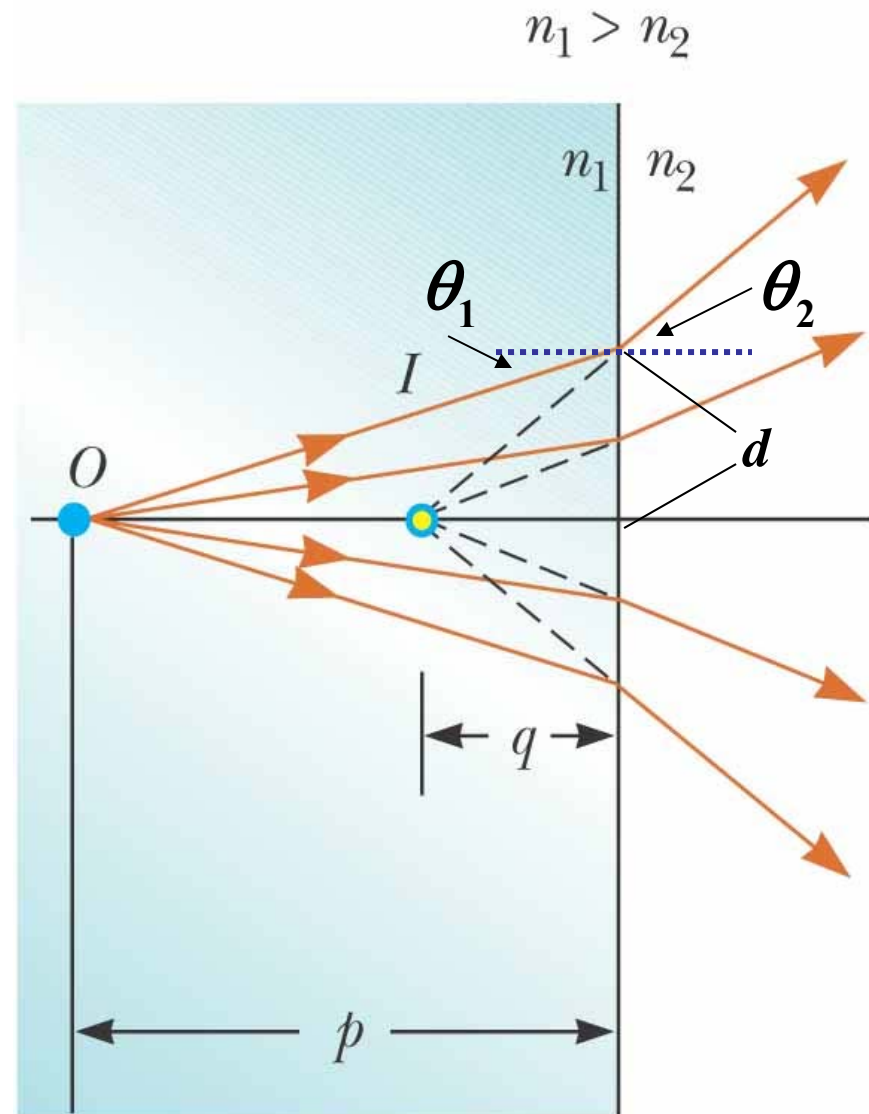
$$\sin \theta_2 \approx \theta_2 \approx \frac{d}{q}$$

$$\sin \theta_1 \approx \theta_1 \approx \frac{d}{p}$$

$$n_2 \frac{d}{q} = n_1 \frac{d}{p}$$

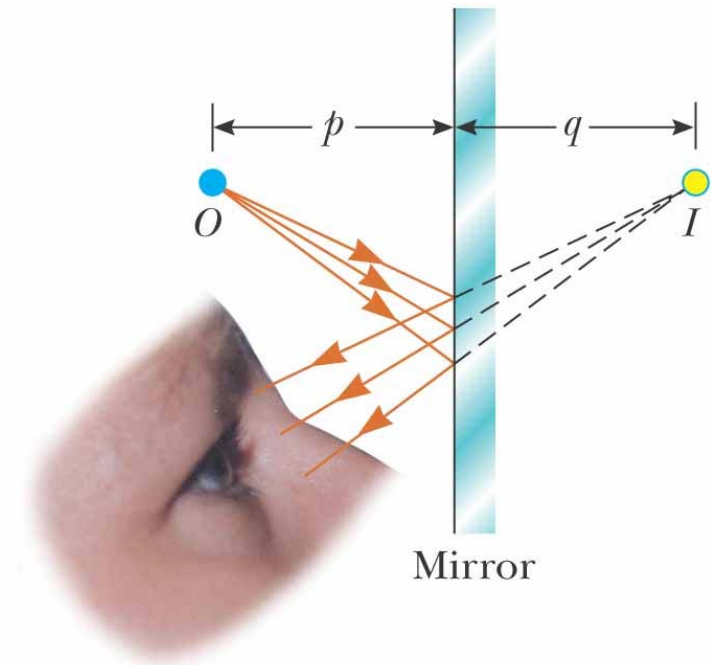
$$q = p \frac{n_2}{n_1}$$

Image is always virtual



Chapter 23

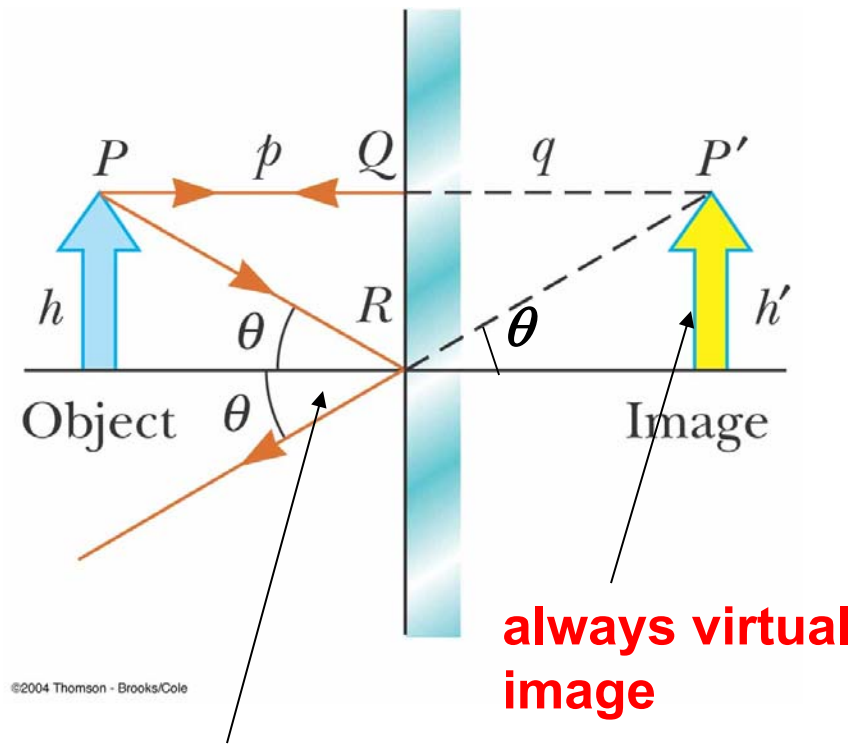
Flat mirror



©2004 Thomson - Brooks/Cole

Flat Mirror

- One ray starts at point P , travels to Q and reflects back on itself
- Another ray follows the path PR and reflects according to the law of reflection
- The triangles PQR and $P'QR$ are congruent
- $h = h'$ - magnification is 1.



The law of reflection

Chapter 23

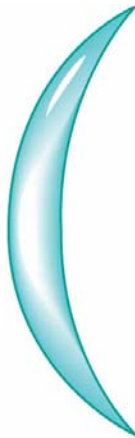
Geometric Optics - Applications: Thin Lenses

Thin Lenses

“Thin” means that the width is much smaller than the *radius of curvature*



Biconvex

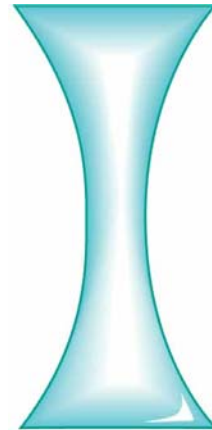


Convex-
concave

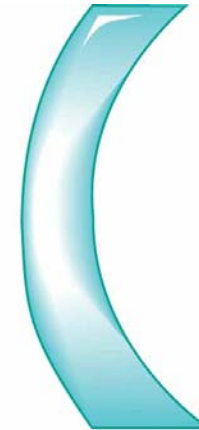
(a)



Plano-
convex



Biconcave



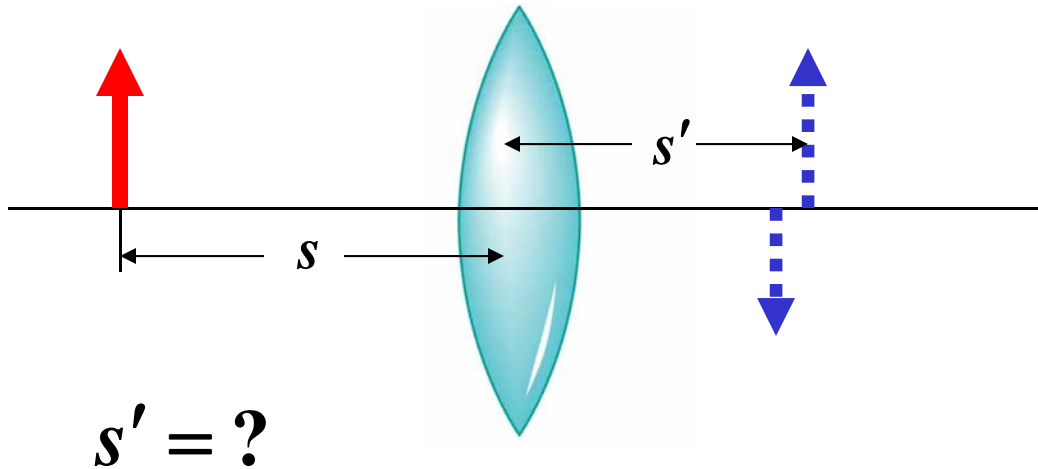
Convex-
concave

(b)



Plano-
concave

Thin Lenses



Thin Lens Equation:

$$\frac{1}{s} + \frac{1}{s'} = \frac{1}{f}$$

Object Distance

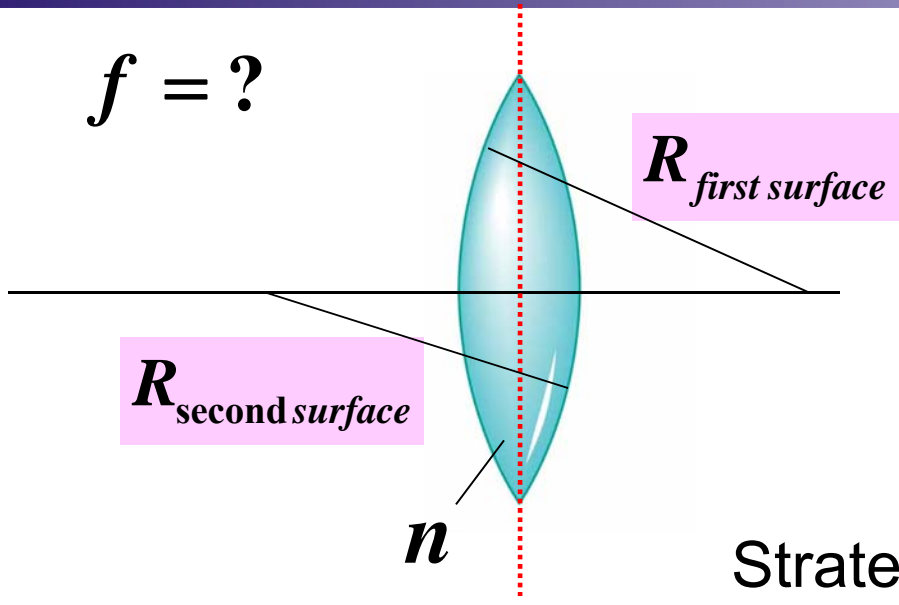
Image Distance

Focal Length

The thin lens is characterized by only *one* parameter – FOCAL LENGTH.

Thin Lenses: Focal Length

$$f = ?$$



Strategy of Finding f :

$$\frac{1}{f} = (n - 1) \left(s_{first} \frac{1}{R_{first\ surface}} + s_{second} \frac{1}{R_{second\ surface}} \right)$$

$$s_{first} = -1 \quad) \quad s_{second} = 1 \quad)$$

$$s_{first} = 1 \quad (\quad s_{second} = -1 \quad ($$

Focal Length: Examples

$f > 0$

$s_1 = 1$

$s_2 = 1$

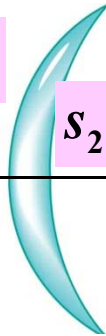


$$\frac{1}{f} = (n-1) \left(\frac{1}{R_1} + \frac{1}{R_2} \right)$$

$f > 0$

$s_1 = 1$

$s_2 = -1$



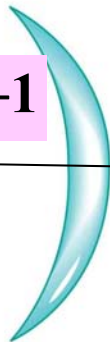
$R_2 > R_1 \quad \frac{1}{R_2} < \frac{1}{R_1}$

$$\frac{1}{f} = (n-1) \left(\frac{1}{R_1} - \frac{1}{R_2} \right)$$

$f > 0$

$s_1 = -1$

$s_2 = 1$



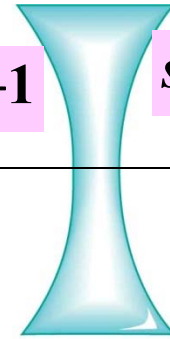
$R_1 > R_2 \quad \frac{1}{R_1} < \frac{1}{R_2}$

$$\frac{1}{f} = (n-1) \left(-\frac{1}{R_1} + \frac{1}{R_2} \right)$$

$f < 0$

$s_1 = -1$

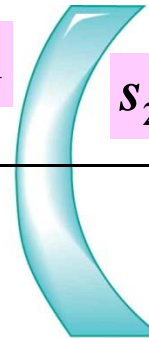
$s_2 = -1$



$$\frac{1}{f} = (n-1) \left(-\frac{1}{R_1} - \frac{1}{R_2} \right)$$

$s_1 = 1$

$s_2 = -1$



$R_1 > R_2$

$$\frac{1}{f} = (n-1) \left(\frac{1}{R_1} - \frac{1}{R_2} \right)$$

$\frac{1}{R_1} < \frac{1}{R_2}$

$f < 0$

Thin Lenses

$$f > 0$$

Converging lens



Biconvex



Convex-concave



Plano-convex

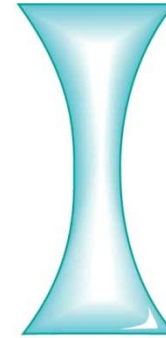
(a)

©2004 Thomson - Brooks/Cole

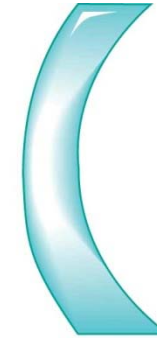
They are thickest in the middle

$$f < 0$$

Diverging lens



Biconcave



Convex-concave



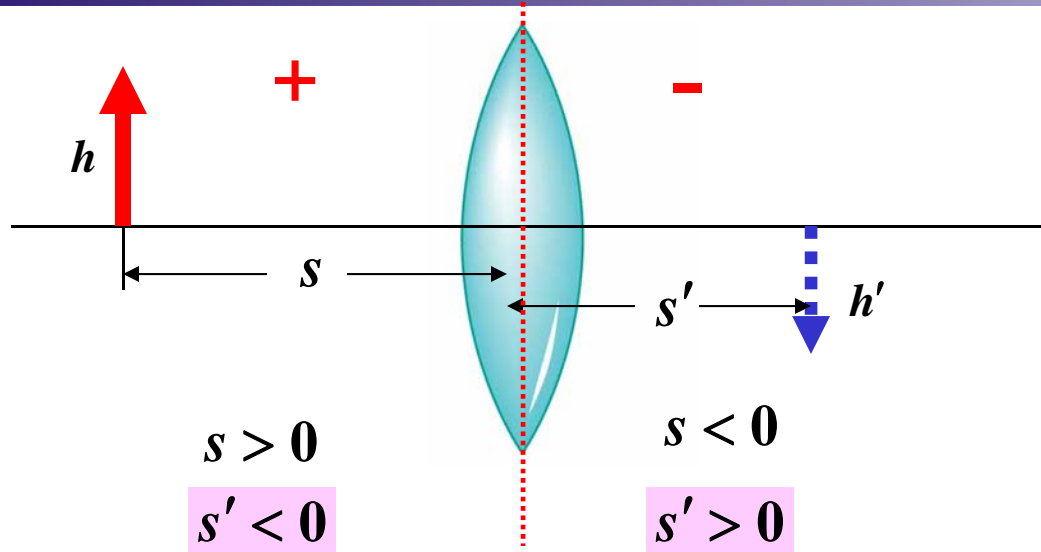
Plano-concave

(b)

©2004 Thomson - Brooks/Cole

They are thickest at the edges

Thin Lenses: Sign Conventions for s, s'



$$\frac{1}{s} + \frac{1}{s'} = \frac{1}{f}$$

Lateral magnification:

$$M = \frac{h'}{h} = -\frac{s'}{s}$$

$h' > 0$

$h' > 0$

Thin Lenses: Numerical Strategy

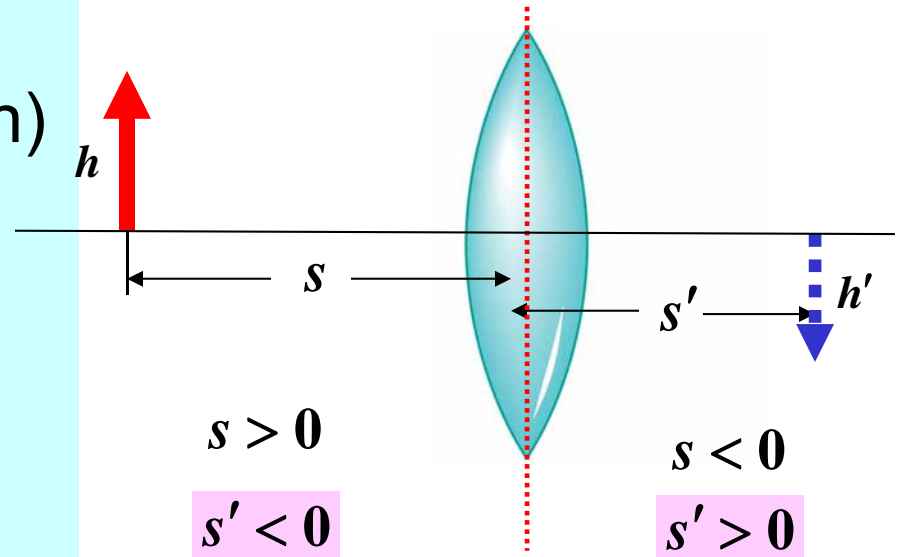
$$\frac{1}{s} + \frac{1}{s'} = \frac{1}{f}$$

- Find the focal length f
- From the Thin Lens Equation find s' (s is known)

$$s' = \frac{1}{\frac{1}{f} - \frac{1}{s}}$$

- From the sign of s' find the position of image
- Find magnification

$$M = \frac{h'}{h} = -\frac{s'}{s}$$



Thin Lenses: Focal Points

Thin Lenses: Focal Points: Converging Lenses

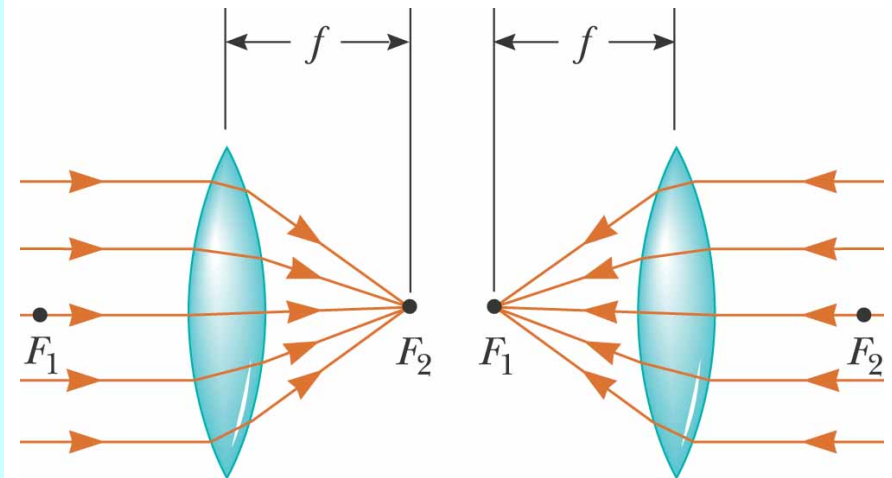
$$\frac{1}{s} + \frac{1}{s'} = \frac{1}{f}$$

- If $s \gg f$, then

$$\frac{1}{s} \ll \frac{1}{f}$$

and

$$s' = \frac{1}{\frac{1}{f} - \frac{1}{s}} = f$$



(a)

©2004 Thomson - Brooks/Cole

- Because light can travel in either direction through a lens, each lens has two focal points.
- However, there is only one focal length

Thin Lenses: Focal Points: Diverging Lenses

$$\frac{1}{s} + \frac{1}{s'} = \frac{1}{f}$$

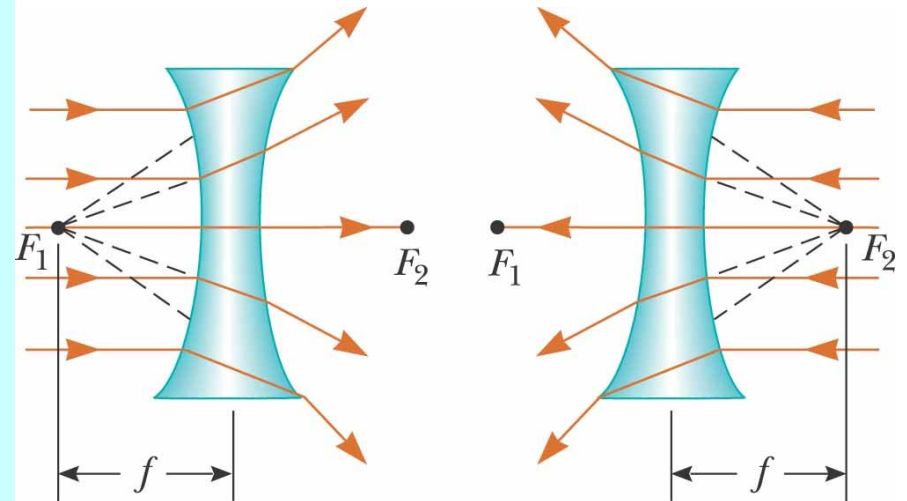
- If $s \gg f$, then

$$\frac{1}{s} \ll \frac{1}{f}$$

and

$$s' = \frac{1}{\frac{1}{f} - \frac{1}{s}} = f$$

- s' is negative



(b)

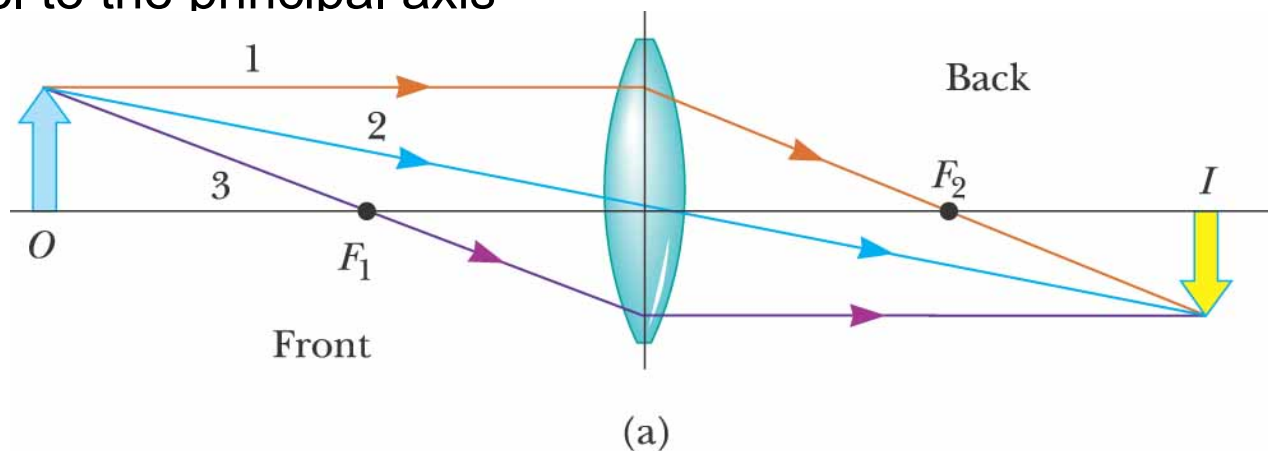
©2004 Thomson - Brooks/Cole

Thin Lenses: Ray Diagram

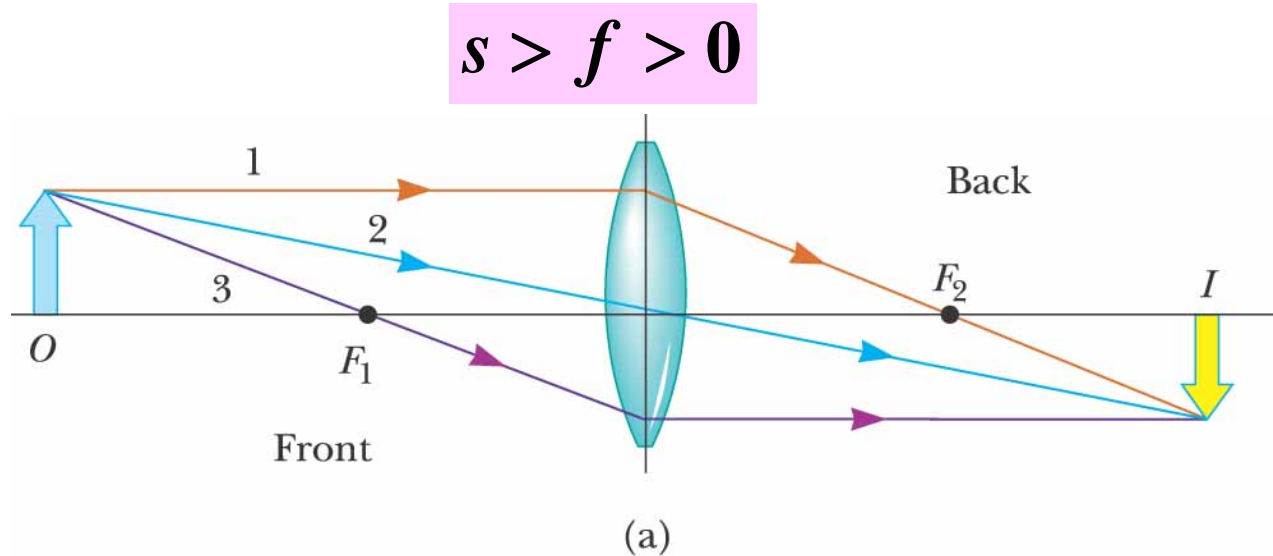
Converging Lenses

For a converging lens, the following three rays (two is enough) are drawn:

- **Ray 1** is drawn parallel to the principal axis and then passes through the focal point on the back side of the lens
- **Ray 2** is drawn through the center of the lens and continues in a straight line
- **Ray 3** is drawn through the focal point on the front of the lens (or as if coming from the focal point if $p < f$) and emerges from the lens parallel to the principal axis



Converging Lenses: Example 1



©2004 Thomson - Brooks/Cole

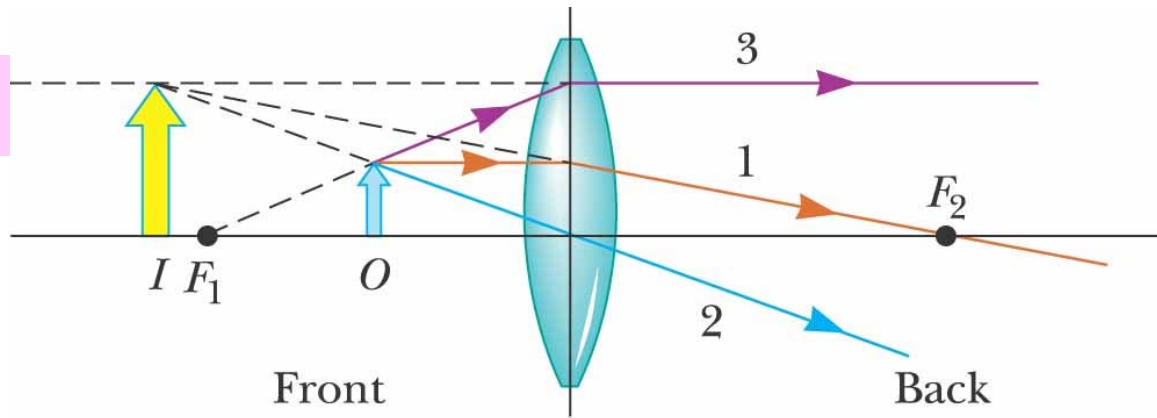
- The image is real
- The image is inverted
- The image is on the back side of the lens

$$s' = \frac{1}{\frac{1}{f} - \frac{1}{s}} = \frac{sf}{s - f} > 0$$

$$M = \frac{h'}{h} = -\frac{s'}{s} < 0$$

Converging Lenses: Example 2

$$f > s > 0$$



(b)

©2004 Thomson - Brooks/Cole

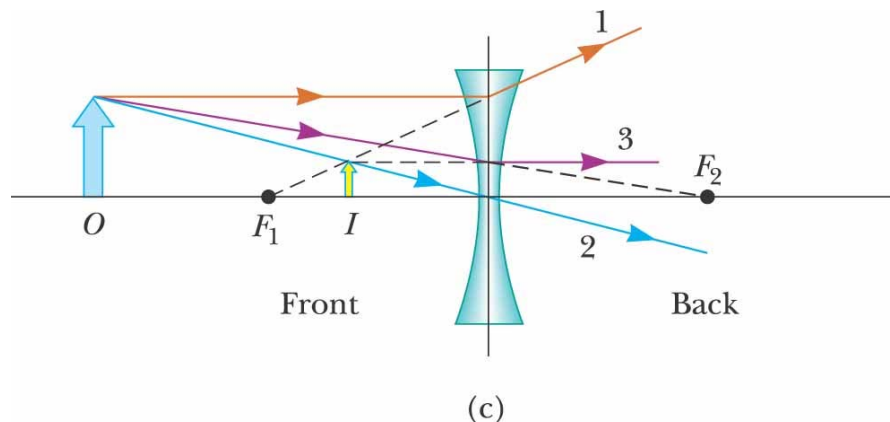
- The image is virtual
- The image is upright
- The image is larger than the object
- The image is on the front side of the lens

$$s' = \frac{1}{\frac{1}{f} - \frac{1}{s}} = \frac{sf}{s - f} < 0$$

$$M = \frac{h'}{h} = -\frac{s'}{s} > 0$$

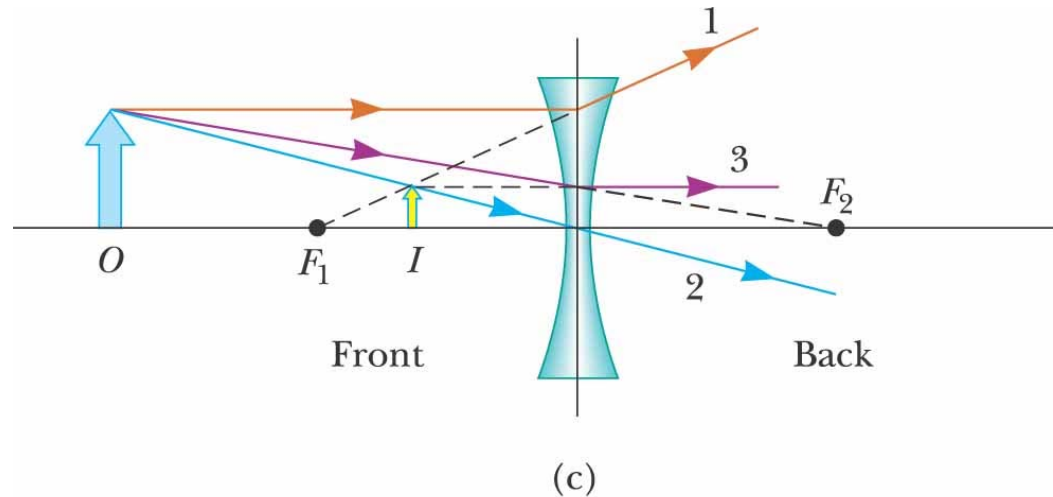
Diverging Lenses

- For a diverging lens, the following three rays (two is enough) are drawn:
 - **Ray 1** is drawn parallel to the principal axis and emerges directed away from the focal point on the front side of the lens
 - **Ray 2** is drawn through the center of the lens and continues in a straight line
 - **Ray 3** is drawn in the direction toward the focal point on the back side of the lens and emerges from the lens parallel to the principal axis



Diverging Lenses: Example

$$f < 0$$



©2004 Thomson - Brooks/Cole

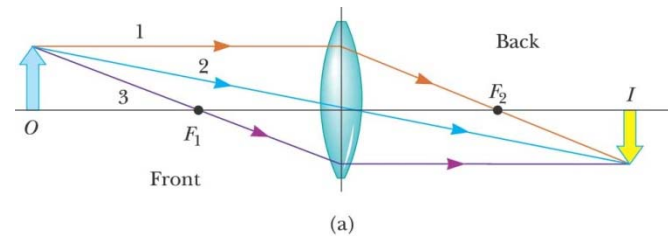
- The image is virtual
- The image is upright
- The image is smaller
- The image is on the front side of the lens

$$s' = \frac{1}{\frac{1}{f} - \frac{1}{s}} = \frac{sf}{s - f} < 0$$

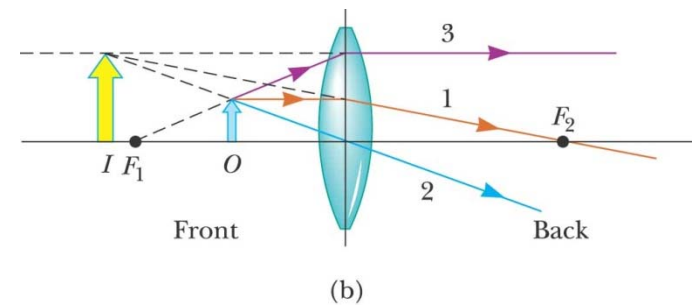
$$M = \frac{h'}{h} = -\frac{s'}{s} > 0$$

Image Summary

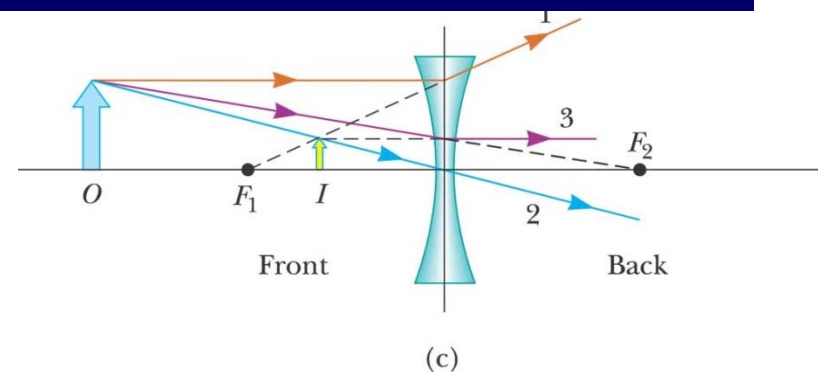
- For a **converging lens**, when the object distance is greater than the focal length ($s > f$)
 - The image is real and inverted



- For a **converging lens**, when the object is between the focal point and the lens, ($s < f$)
 - The image is virtual and upright

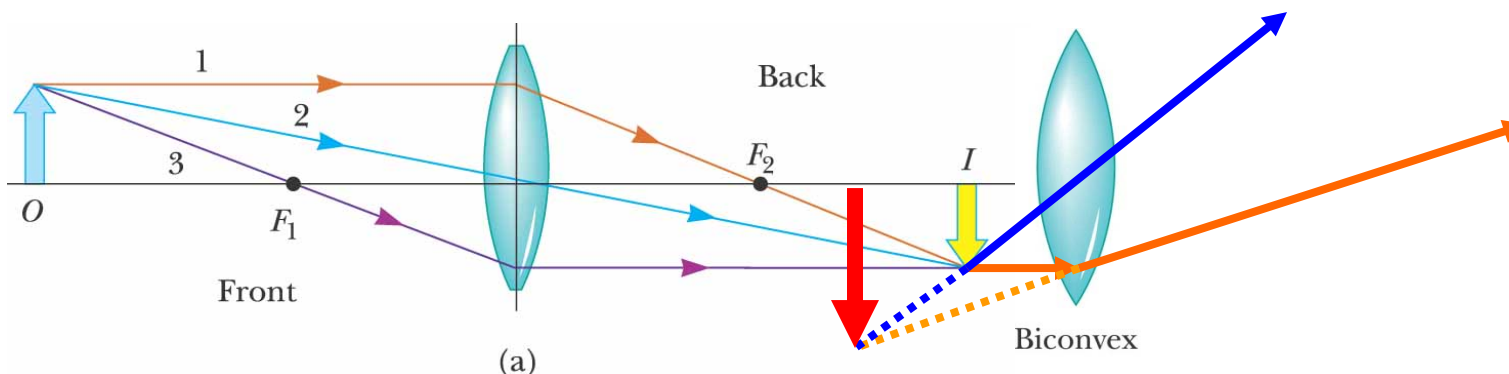


- For a **diverging lens**, the image is always virtual and upright
 - This is regardless of where the object is placed



Combination of Two Lenses

- The image formed by the **first** lens is located as though the **second** lens were not present
- *The image of the first lens is treated as the object of the second lens*
- Then a ray diagram is drawn for the second lens
- The image formed by the second lens is the **final** image of the system
- If the image formed by the first lens lies on the back side of the second lens, then the image is treated as a *virtual object* for the second lens
 - **s** will be negative
- The overall *magnification* is the product of the magnification of the separate lenses

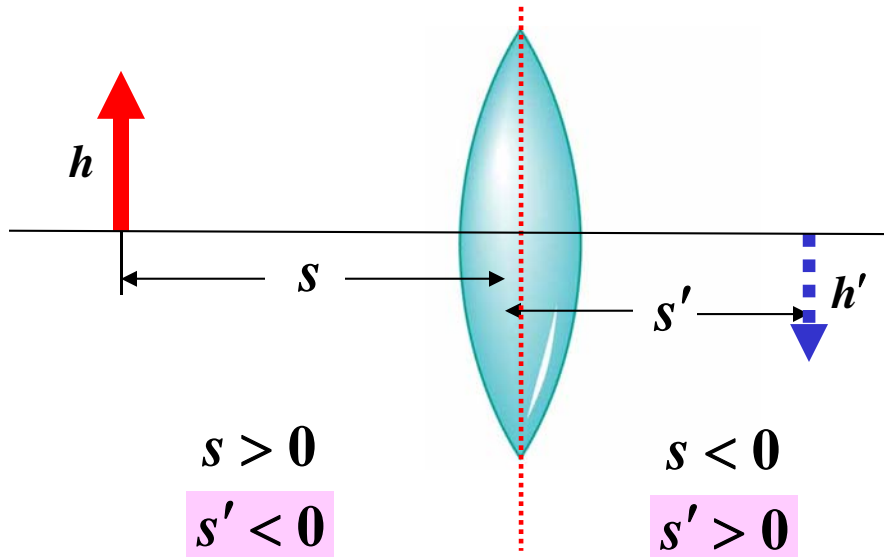
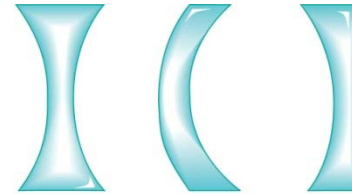


$$\frac{1}{f} = (n - 1) \left(s_1 \frac{1}{R_1} + s_2 \frac{1}{R_2} \right)$$

$f > 0$

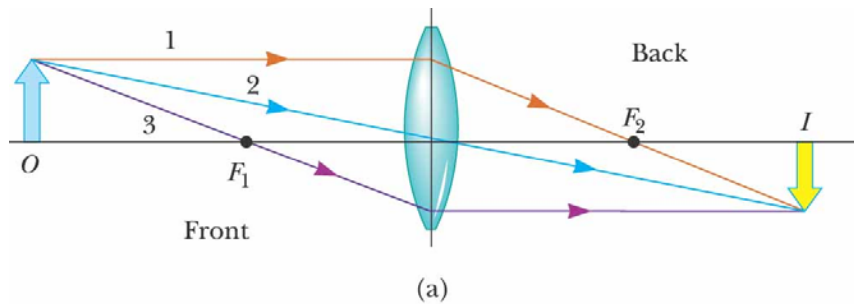


$f < 0$

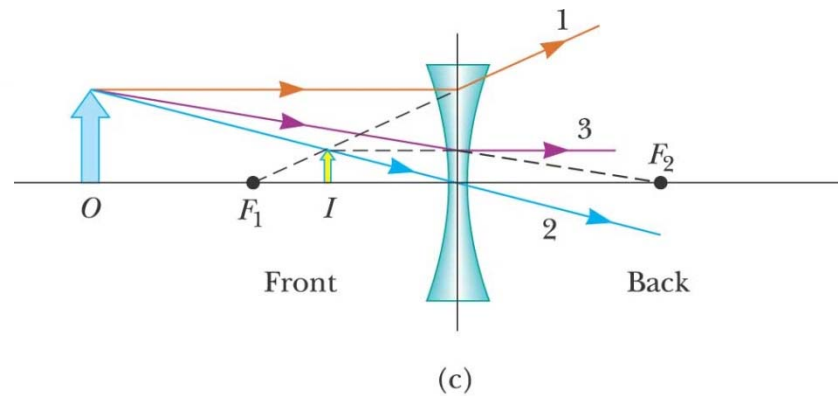


$$\frac{1}{s} + \frac{1}{s'} = \frac{1}{f}$$

$$M = \frac{h'}{h} = -\frac{s'}{s}$$



©2004 Thomson - Brooks/Cole



©2004 Thomson - Brooks/Cole

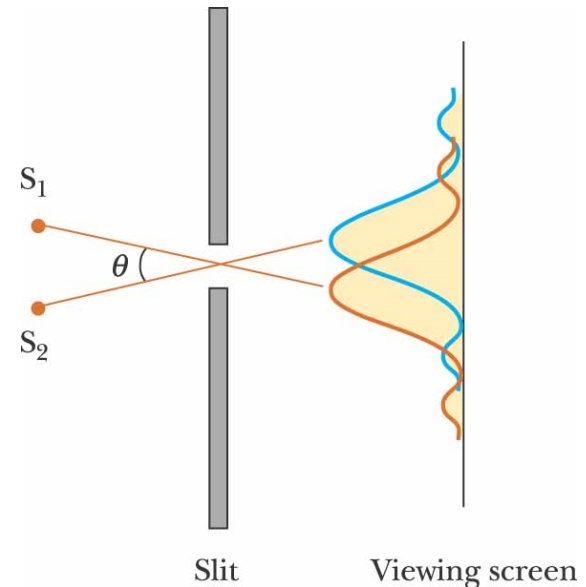
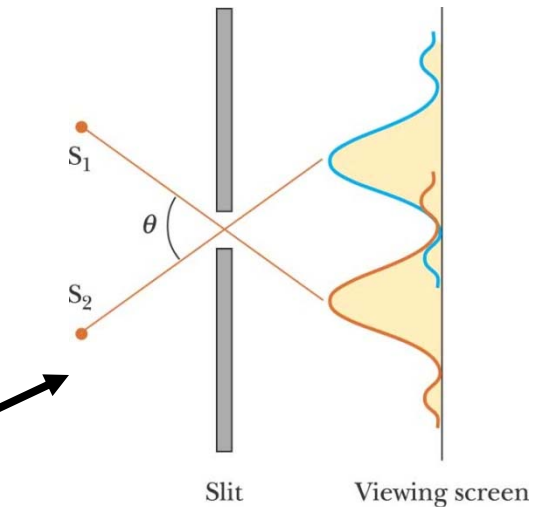
Resolution

Resolution

- The ability of optical systems to distinguish between closely spaced objects
- If two sources are far enough apart to keep their central maxima from overlapping, their images can be distinguished

The images are said to be *resolved*

- If the two sources are close together, the two central maxima **overlap** and the images are **not resolved**



Resolution, Rayleigh's Criterion

Rayleigh's criterion:

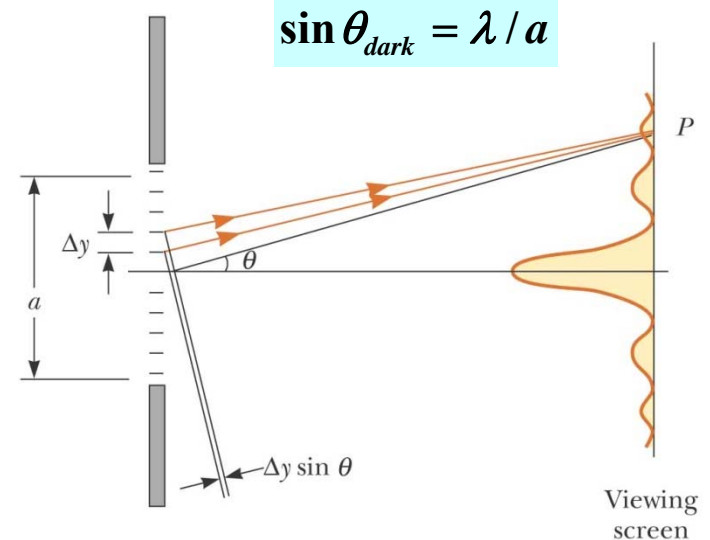
When the *central maximum* of one image falls on the *first minimum* of another image, the images are said to be just resolved

Resolution of a slit:

- Since $\lambda \ll a$ in most situations, $\sin \theta$ is very small and $\sin \theta \sim \theta$
- Therefore, the limiting angle (in rad) of resolution for a slit of width a is

$$\theta_{\min} = \theta_{\text{dark}} = \lambda / a$$

- To be resolved, the angle subtended by the two sources must be greater than θ_{\min}



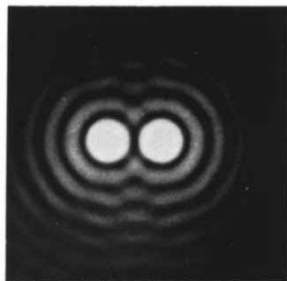
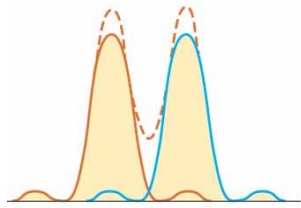
Resolution: Circular Aperture

- The diffraction pattern of a **circular aperture** consists of a **central bright disk** surrounded by progressively fainter bright and dark rings
- The limiting angle of resolution of the circular aperture is

$$\theta_{\min} = 1.22 \frac{\lambda}{D}$$

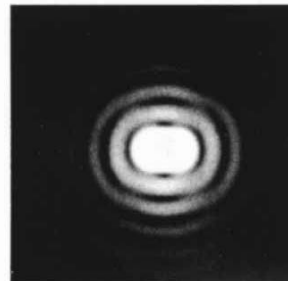
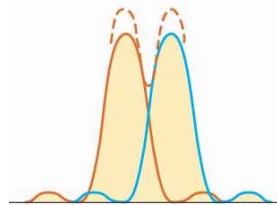
– D is the diameter of the aperture

The images are well resolved



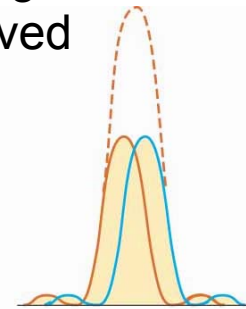
(a)

The images are just resolved



(b)

The images are unresolved



(c)